

Measuring [sub-] mm range differences caused by polarization effects

or

What can we expect from GNSS ?

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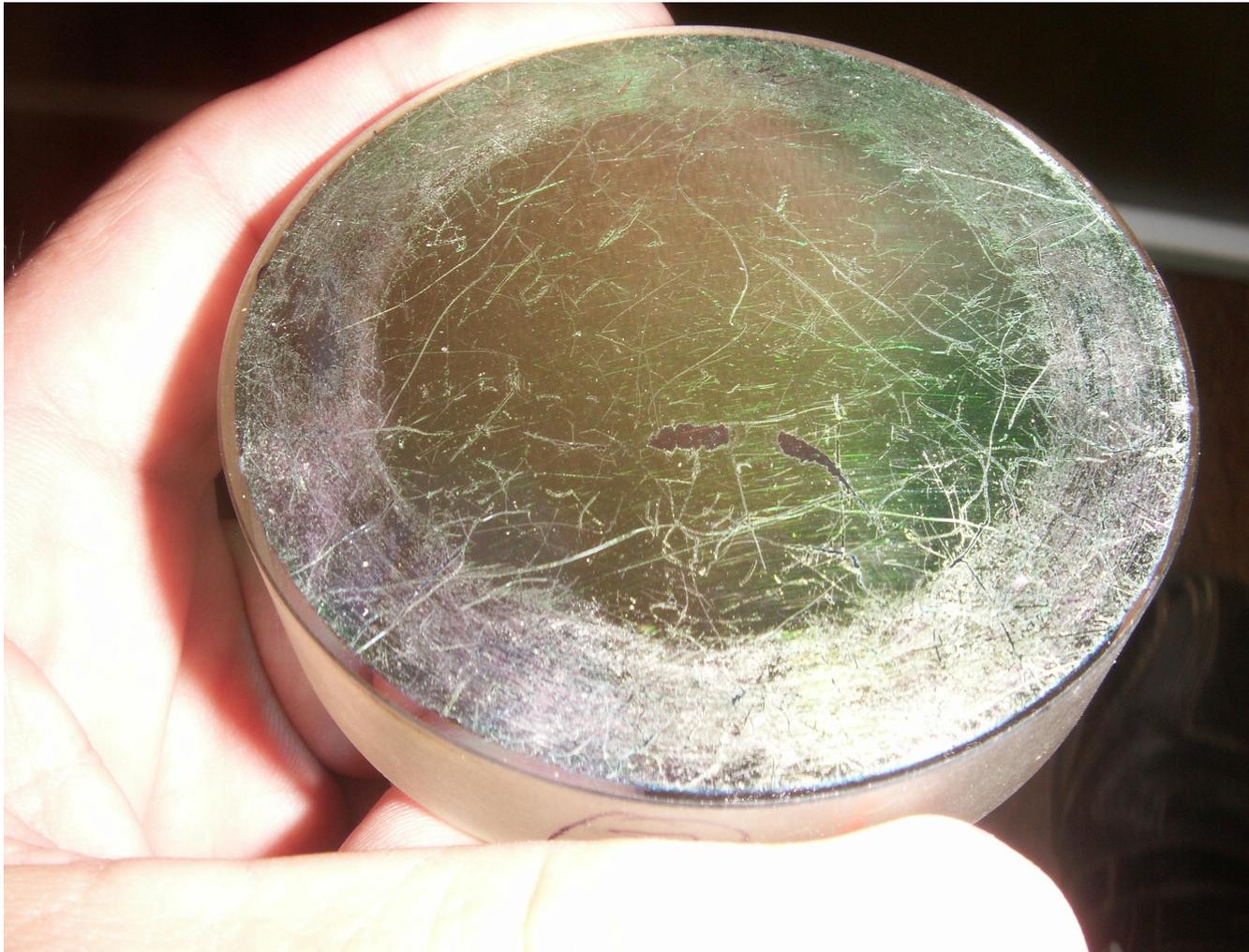
Overview

- Improvements for HEO satellite tracking in Graz
 - #1: Filter removed for night time HEO tracking (2010)
 - #2: dichroic mirror replacement (March 2011)

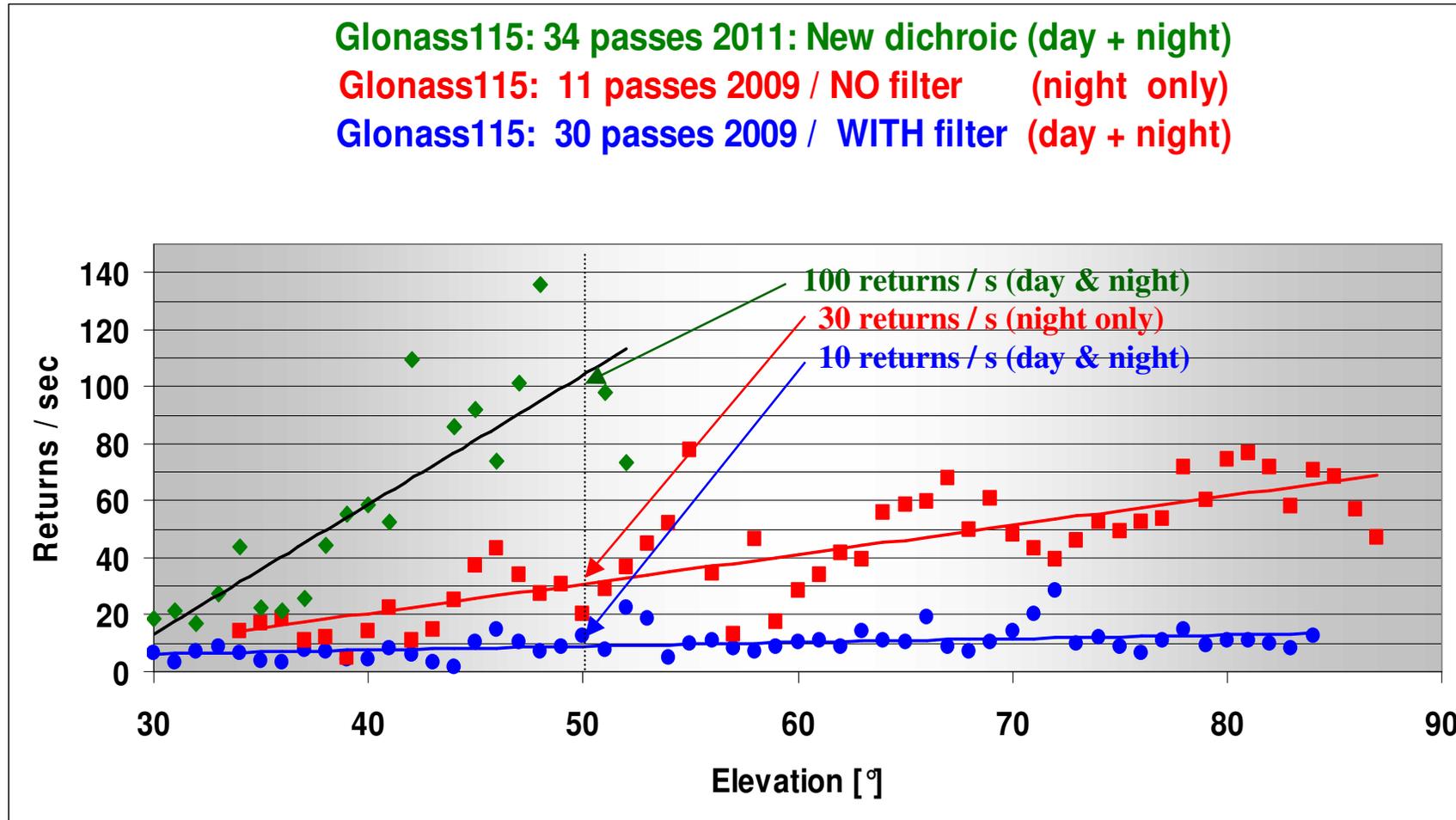
Tracking software improvements

- Compass M1 Polarization tests
 - Tracking full CompassM1 passes (> 4 hours, high elevation)
 - Switching polarization plane during tracking in 1 minute intervals
 - Forming 1-minute NPs
 - Measuring effects of polarization plane orientation

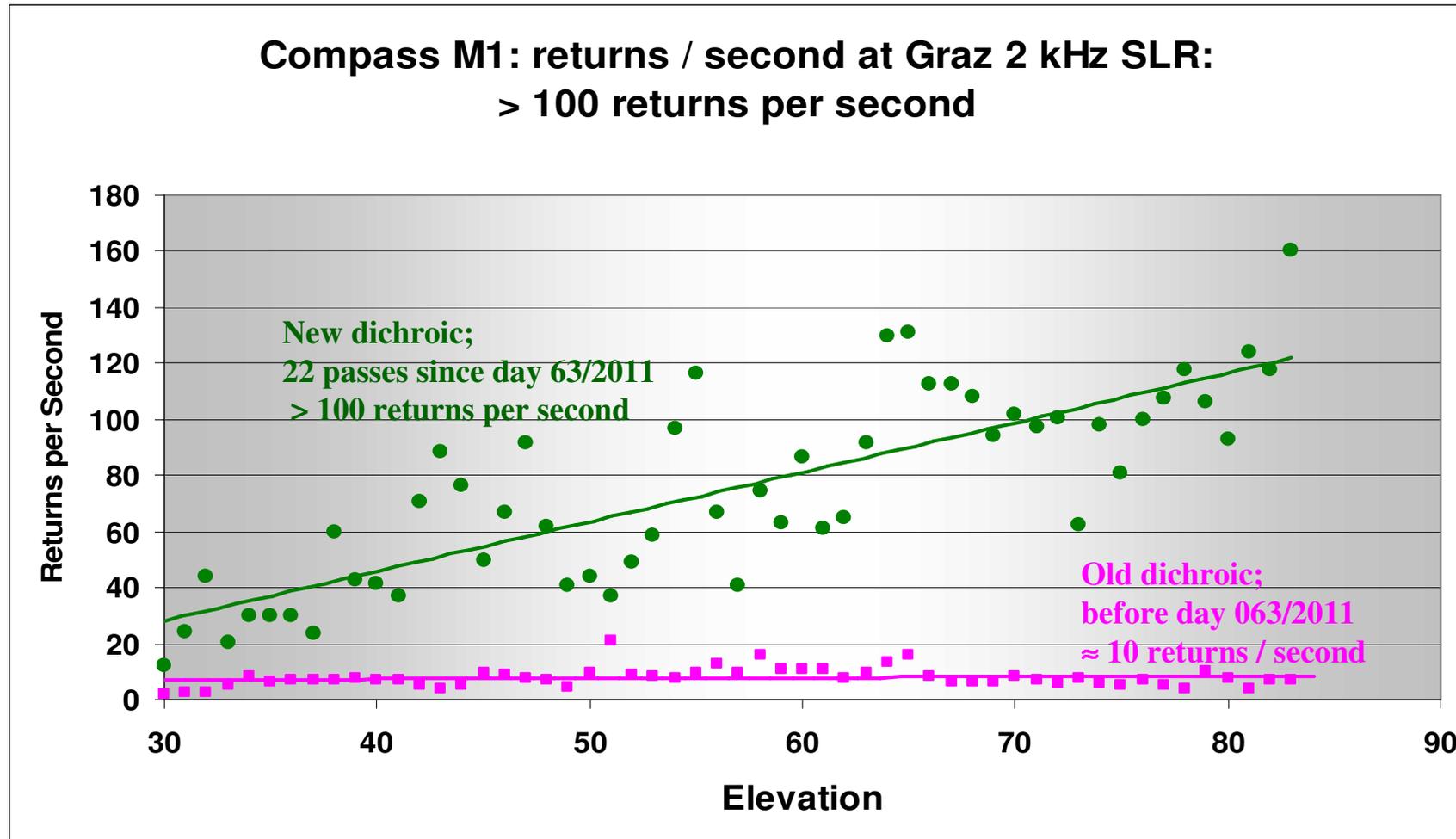
- Since 2010 we are removing the 0.3 nm filter for night time HEO passes
 - This daylight filter has about 35% transmission
 - This improved HEO return rates already by a factor of 3
- In March 2011 we replaced our old (1982!!!) dichroic mirror
 - NERC colleagues found (and tested) an excellent new dichroic
 - This new dichroic transmits $> 95\%$ at 532 nm
 - Almost ZERO polarization dependence
- Software / Tracking routines: Minor improvements
- All together: About 10 times higher return quotes from HEO satellites



„Chris suggested you might have been using it as an ice hockey puck 😊...“



Graz kHz SLR: HEO Return Quotes for 2 kHz, and 400 μ J/shot
 Small improvements can have big effects (sometimes 😊 ...)



Graz kHz SLR: HEO Return Quotes for 2 kHz, and 400 μ J/shot
Factor of 10 Improvement ...

- Dave Arnold has said at several recent ILRS meetings that there may be differences in target signatures due to the state of polarization of the beam incident on the target.
- Effects only on uncoated retros – e.g. Lageos 1 & 2 and ETS 8.
- For **LINEAR** polarization on LAGEOS, cross section varies between 10 and 21×10^6 m², and range correction by 3.2 mm, depending upon angle between polarization and velocity aberration vectors. (Arnold, private comm., 15 Sep 2007)
- For **CIRCULAR** polarization, there is little such variation.
- Are differences between linear and circular polarization of incident laser beam measurable in practice?

John Luck, Victoria Smith, Chris Moore: „Circular Polarization Experiment“
ILRS Fall 2007 Workshop Grasse

- Now a new satellite Compass M1 has been launched: UNCOATED retros !
- We tracked a few full passes of CompassM1 (about 4 hours);
 - This gives about 2 Million points (2 kHz, 400 μ J pulses)
- We switched polarization plane during tracking in 1 minute intervals;
 - 1 Minute with POL plane ALONG orbit of CompassM1 (even minutes)
 - 1 Minute with POL plane ACROSS orbit of CompassM1 (odd minutes)
- We formed 1-minute NPs (about 250 NPs for 1 pass)
- We see the effects of POL plane orientation at least on part of the passes

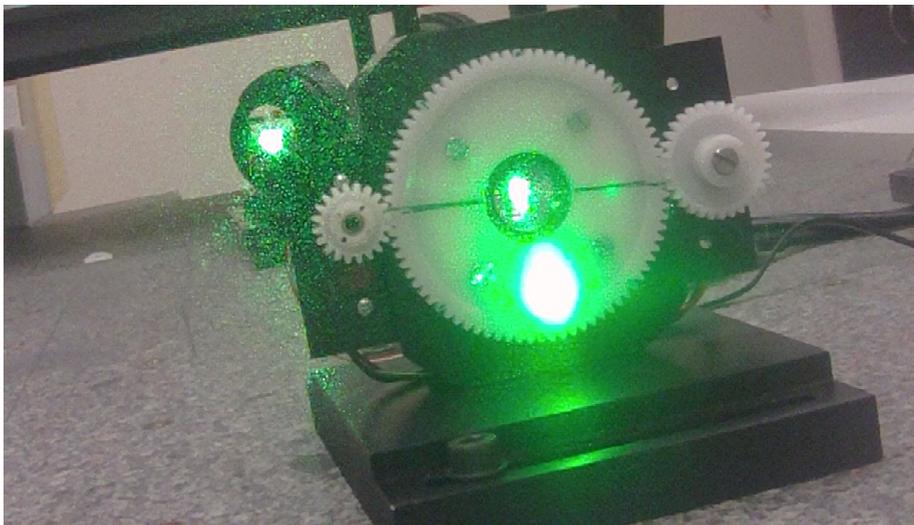
Satellites with uncoated CCR: LAGEOS-1, LAGEOS-2: Satellite signature is too big
 ETS-8: Not visible from Graz

NEW: CompassM1: Uncoated CCR; good efficiency

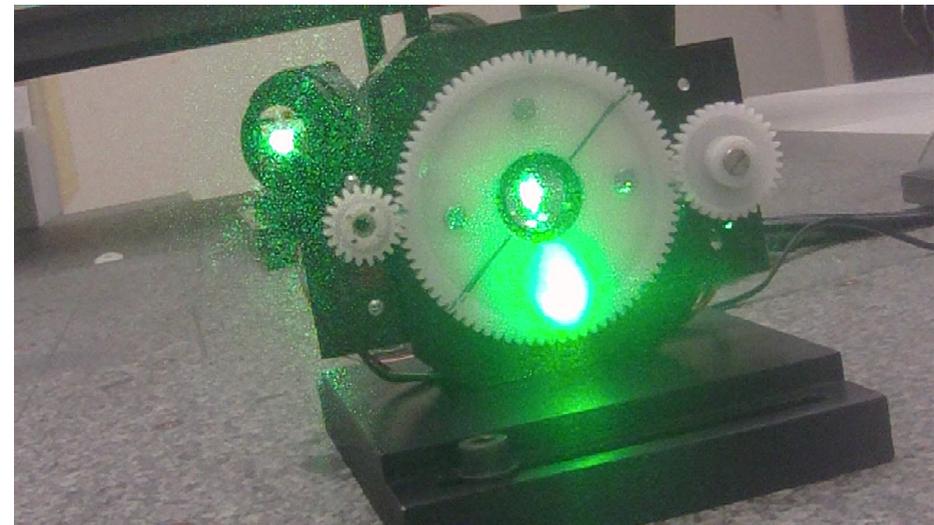


31.6 x 28 cm hexagonal array; 2.5 kg;
 42 CCR; each 33 mm diameter;
 fused silica;
 UNCOATED ☺

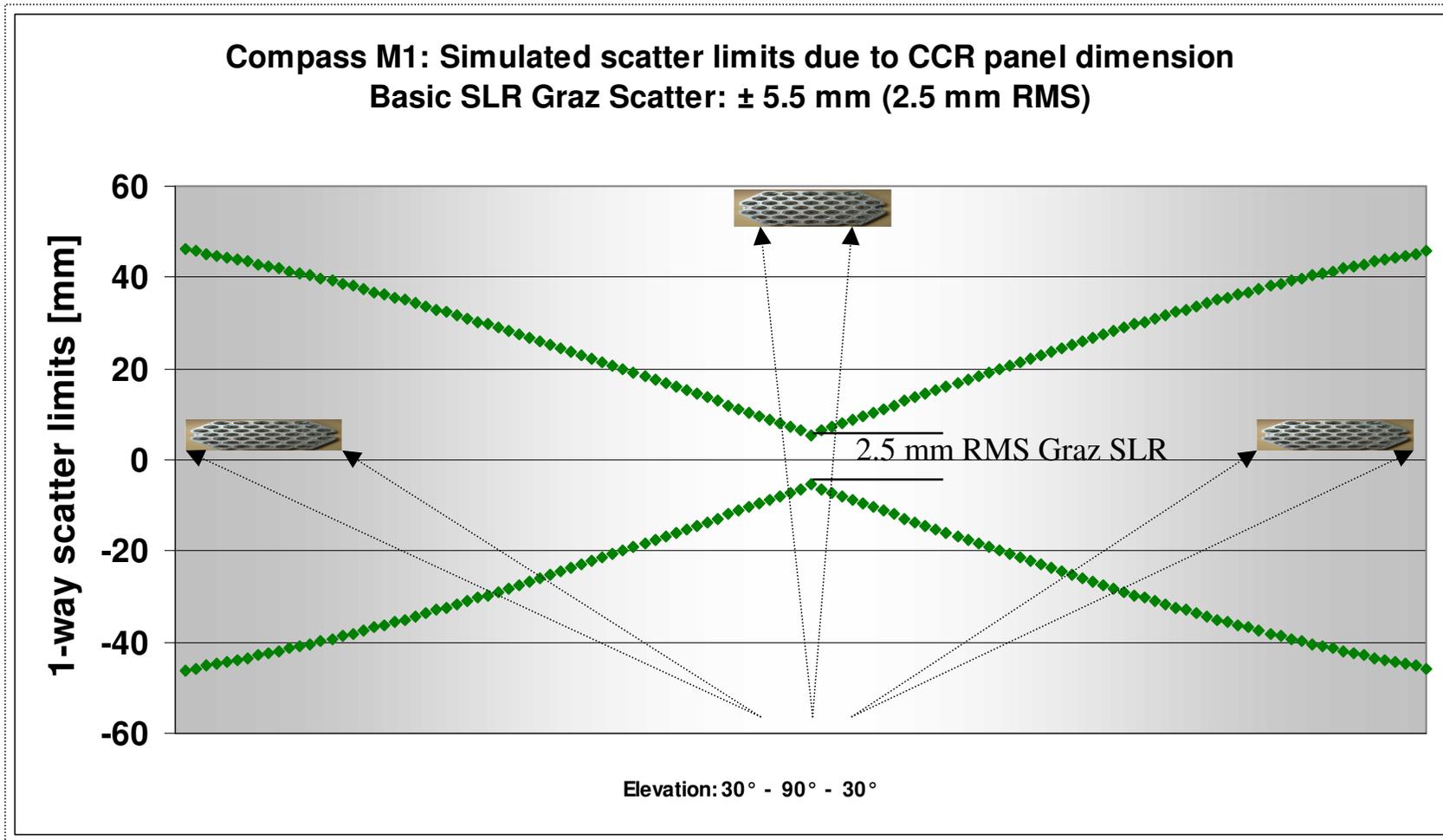
- We installed a $\lambda/2$ waveplate on the laser table: rotation by α rotates POL plane by 2α
- Rotation is PC controlled; POL plane orientation can be chosen:
 - To compensate for mount / telescope motion; and/or
 - To adjust for the satellite orbital motion, resp. its velocity aberration vector
- For the ‚Arnold‘ experiment, the plate was rotated each minute by 45° (back and forth);
- This rotated the linear POL plane by 90° ; Goal:
 - In each ODD minute: POL plane orientated ACROSS orbit (‚Arnold‘ angle \odot : 90°)
 - In each EVEN minute: POL plane orientated ALONG orbit (‚Arnold‘ angle \odot : 0°)



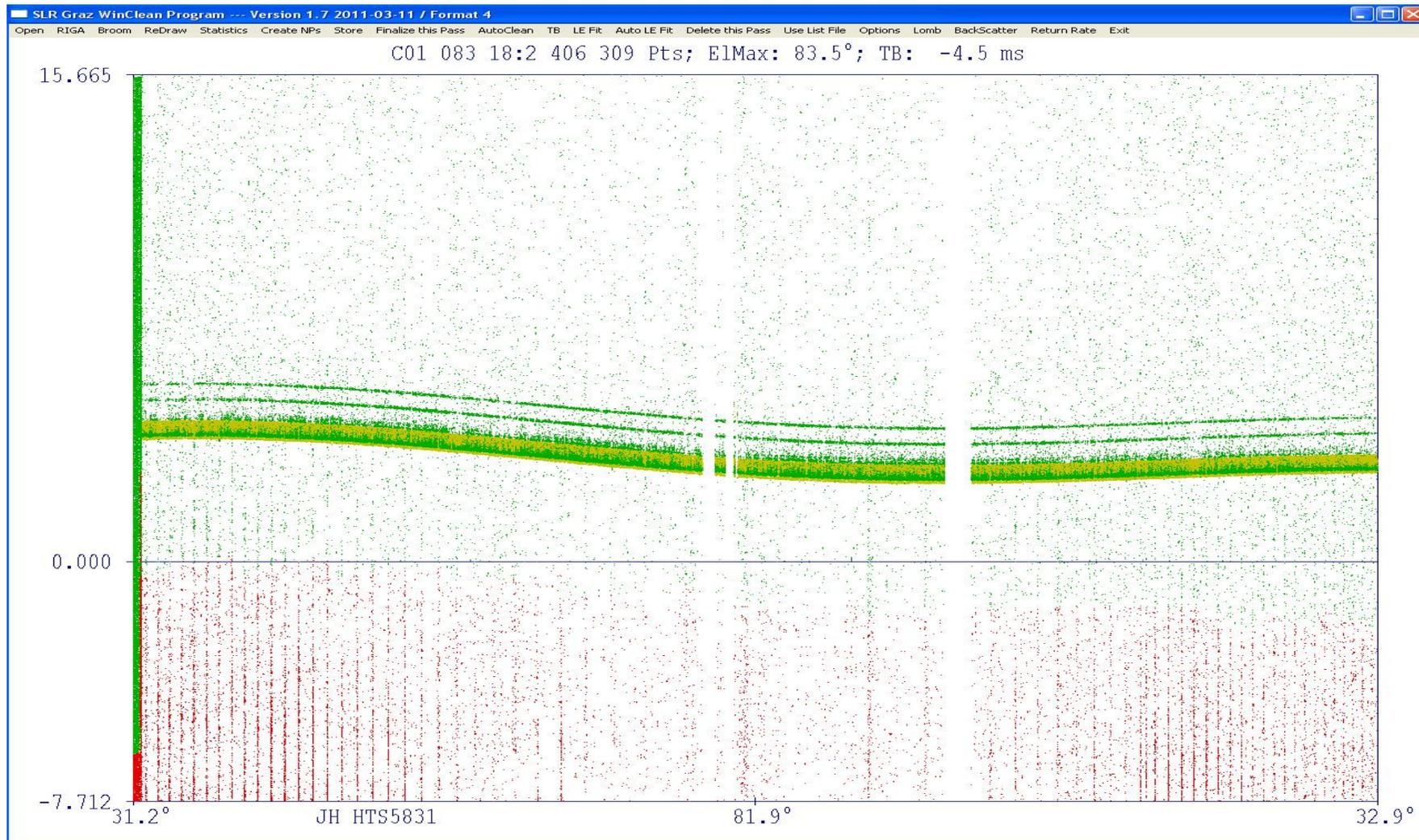
$\lambda/2$ waveplate at 0° (on laser table);
IWF/ÖAW GRAZ



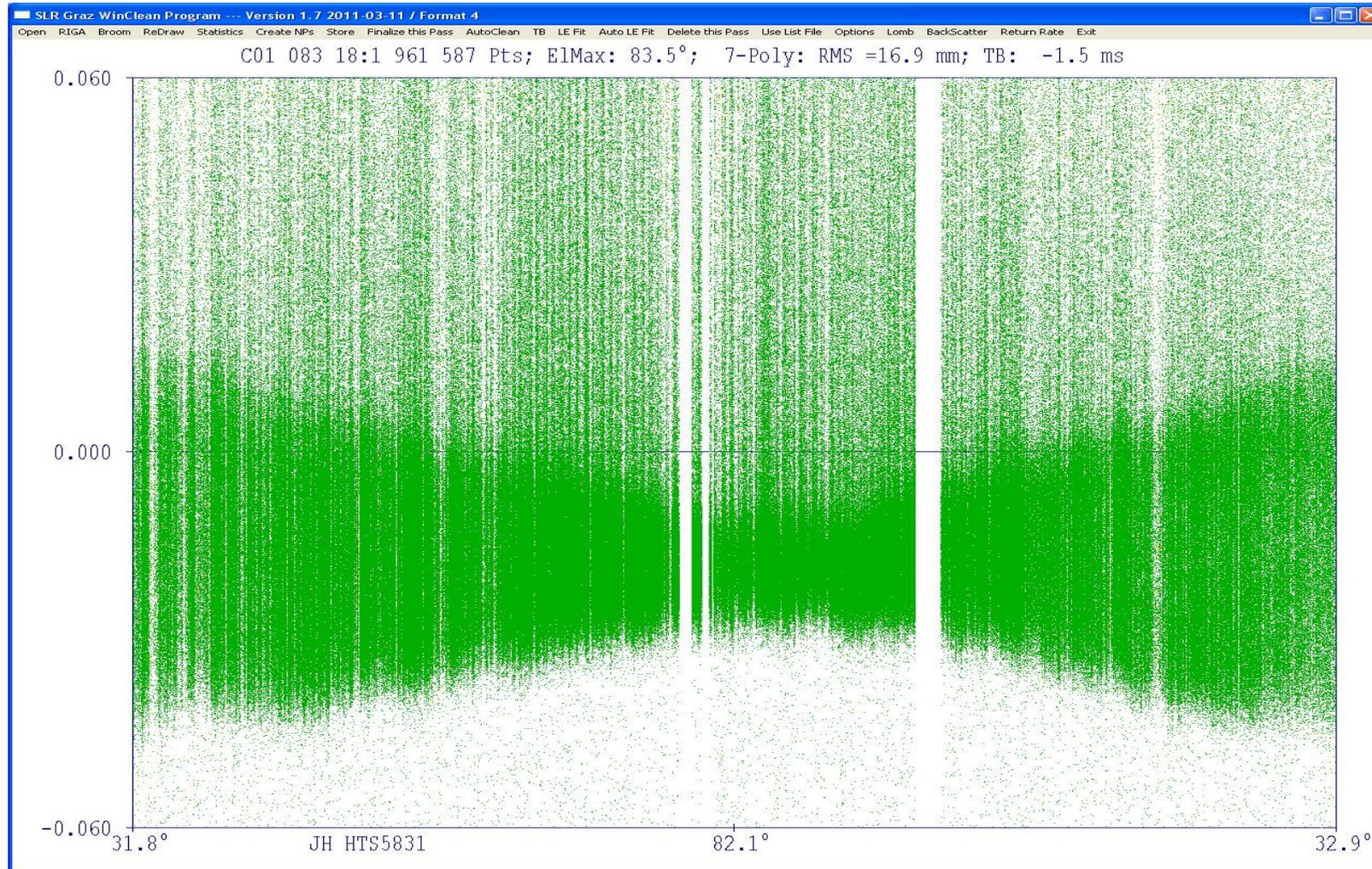
$\lambda/2$ waveplate at 45°



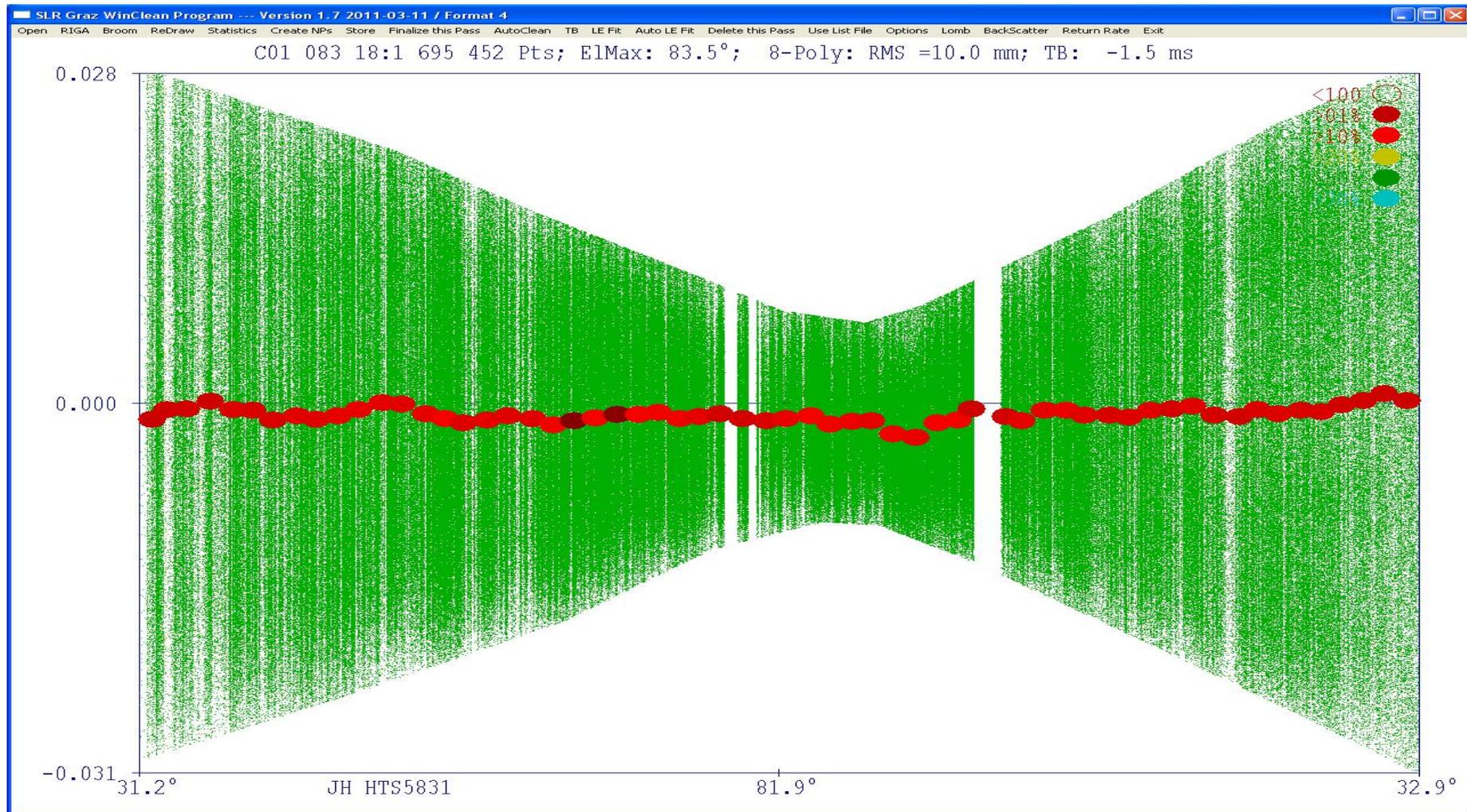
- At 90° Elevation: Minimum scatter of 2.5 mm RMS
- At lower elevation: Increasing scatter due to panel geometry / dimensions



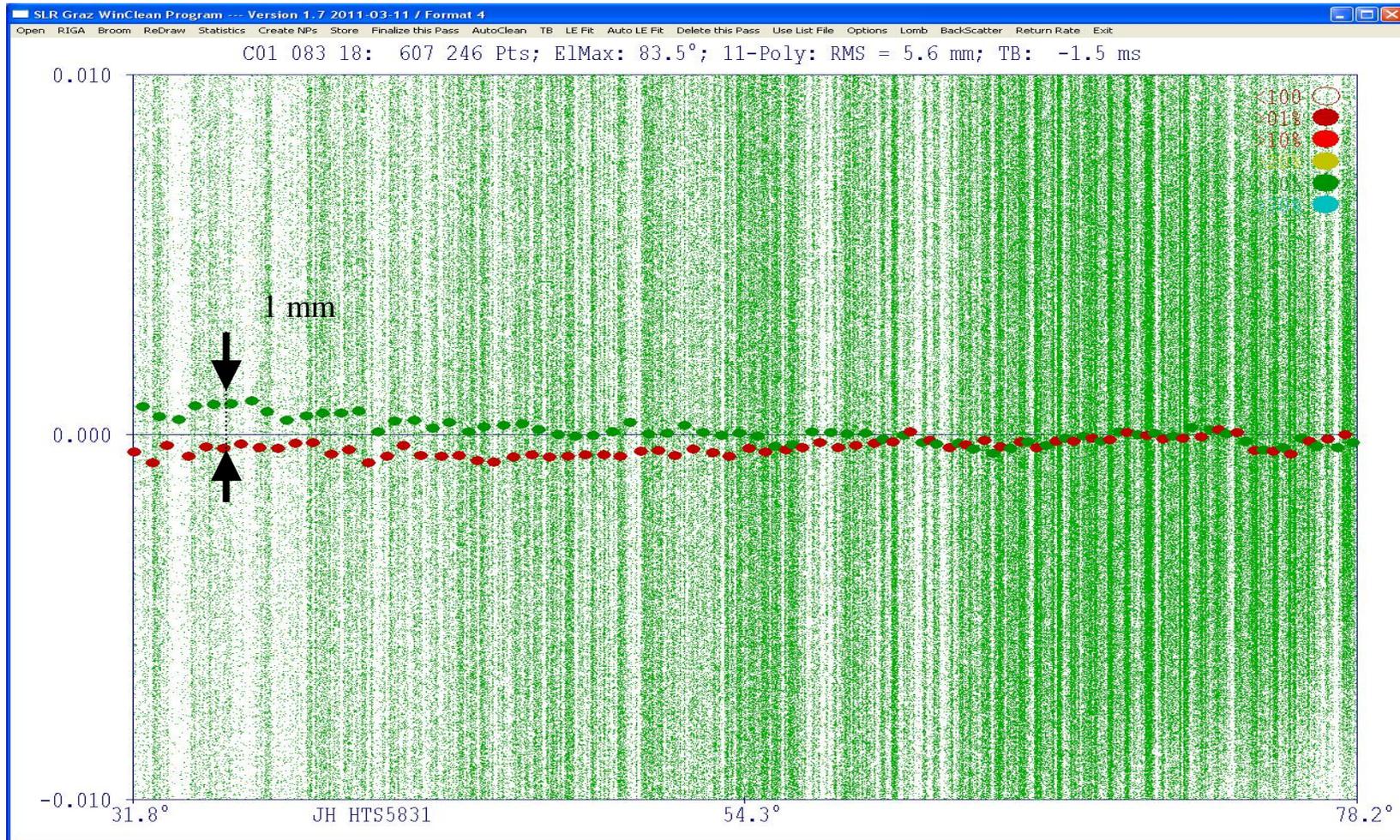
- About 4 hours of a Compass-M1 pass; max elevation: 83.5°
- < 3% post train (due to slight leakage of laser regenerative amplifier)
- Still some – slight – overlaps visible



- Main Return Line clearly visible; C-SPAD after-pulsing: Increased noise AFTER main track
- Panel geometry becomes visible; still almost 2 million points



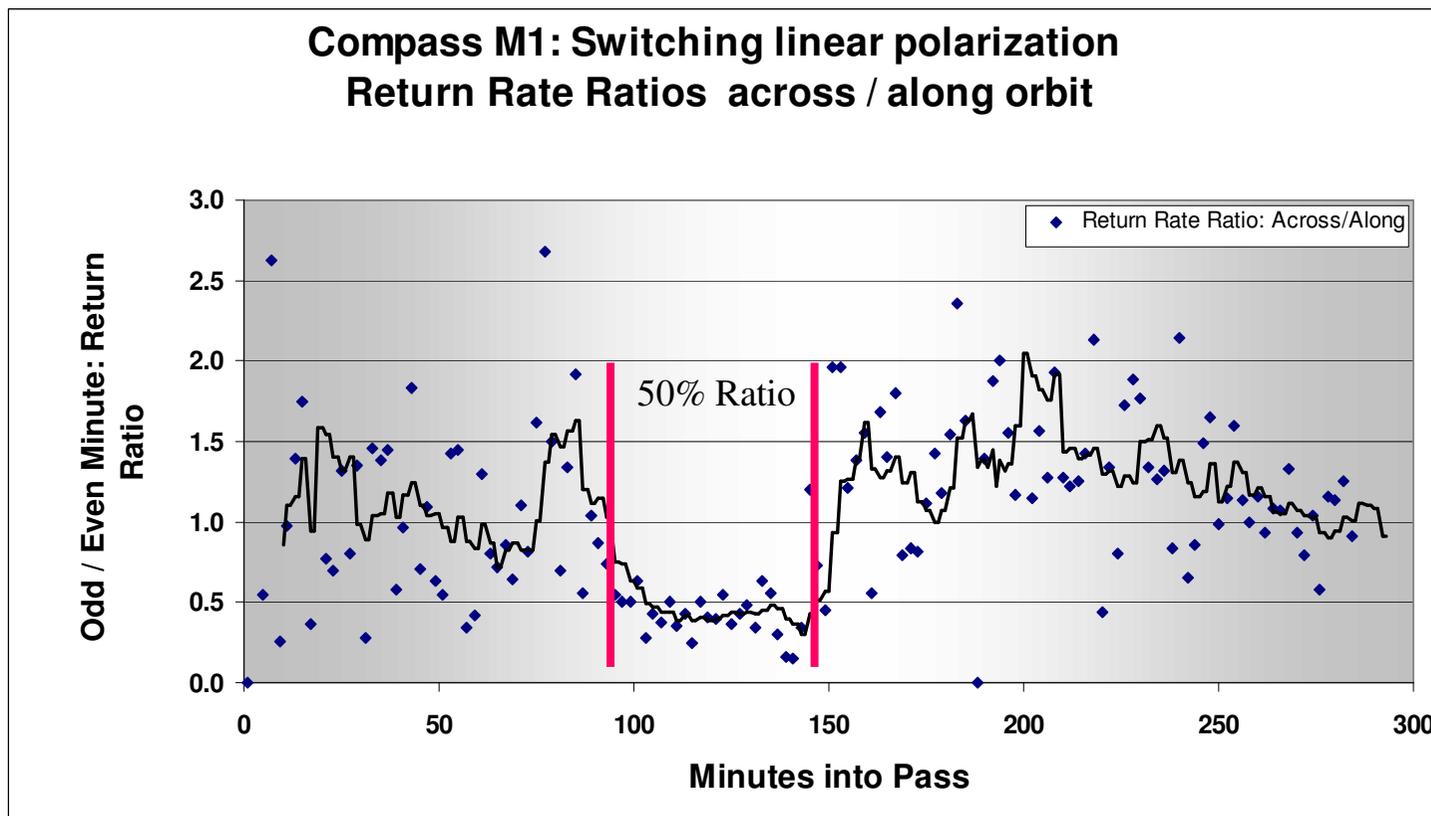
- Standard / routine handling: Removing noise, sending 5-minute NPs to ACs
- Although significant satellite signature: NPs are VERY accurate with the 2 - kHz system ...



- Green NPs: ODD minutes, POL plane *across* orbit; red NPs: EVEN minutes; POL plane *along* orbit
- Unfortunately, the effect disappeared towards CA: (error in our ‚Arnold‘-angle calculations ☹ ??)

Another prediction: „ [Lageos] cross section will vary between 10×10^6 and 21×10^6 m², depending upon angle between polarization and velocity aberration vectors („Arnold angle“)

We calculated the return ratio between *odd* (=ACROSS) and *even* (=ALONG) minutes; the results are not complete, but during the 50' around CA the ratio is rather constant at 0.5



- *Conclusion 1:*

- GNSS Satellites allow sub-mm NPs with kHz SLR techniques
- With a 2 kHz / 400 μ J system, some 10 to > 100 returns / s can be achieved
- With fast switching between satellites, this will allow tracking of ALL GNSS satellites (including future Galileo etc.)

- *Conclusion 2* (only CompassM1 – und future Compass satellites – and Lageos 1&2):

- Linear polarized laser pulses on *uncoated* retro-reflectors affect the measured ranges;
- This effect is up to a few mm
- It can be avoided by inserting a $\lambda/4$ waveplate on the laser table:
This changes linear polarization into circular polarization (will be tested in Graz)

Thank you 😊



